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A VERY SHORT-TERM LOAD FORECASTING IN TIME OF PEAK LOADS USING INTERVAL TYPE-2 FUZZY INFERENCE SYSTEM: A CASE STUDY ON JAVA BALI ELECTRICAL SYSTEM

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Abstract

The process of generation, transmission and distribution of electricity to the customer must be operated properly [10] ey are related to economic problems. One of these planning processes is a very short term forecasting. A very short term load forecasting was done one day [12] re the day of operation that has a planning time interval every 30 minutes. Fuzzy logic is one of the methods in very short term load forecasting. This study used Interval Type-2 Fuzzy Inference System (IT-2FIS) since it has high flexibility. IT-2FIS is the development of the Footprint of Uncertainty (FOU) at IT-1FIS method that has a very flexible advantage in changing FOU, so it is supportive to form the initial processing of time series data, computation, simula [14] and system model validation. The implementation of IT-2 FIS was on a very short term load forecasting in peak load time. This study found an average of very short term forecasting error rate on the fourth Friday in October 2015 and 2016 is 0.71% when IT-2 FIS was implemented. This result is better than using IT-1 FIS whose average of very short term forecasting error rate is 1.11%.

Keywords: IT-1 FIS, IT-2 FIS, Very short term load forecasting.

1. Introduction

Good forecasting is required in an operational arrangement of a power system. This electrical system operation starts from the generation system, transmission system and distribution system to the customer [1]. This integration is carried out at an electrical agency tasked with forecasting loads and regulating power systems [2-4]. On the forecasting of electrical power, there are at least three kinds of forecasting: long term forecasting, short forecasting and very short term forecasting. Long-term power load forecasting is done at the annual period and is conducted for planning maintenance, replacing tool plants and labour and for planning needs of the fuel operations for one year. Short-term electric load forecasting, i.e., forecasting a daily electricity load to find out the daily peak loads that occur in a year in order to make daily power generation planning for one year. Meanwhile, the forecasting of very short term electric load refers to an electrical load forecasting that is conducted every 30 minutes daily. Jamaaluddin and Sumarno [1] reported that a very short term load forecasting is done one day before the day of loading to plan the electric power generation for the next 14y. According to Jamaaluddin and Robandi [5], this electrical institute performs a short-term and very short-term forecasting. This load forecasting is needed in relation to the economic problem of generation.

Previous researchers using Fuzzy Logic [6-8] have done optimization of short-term loads forecasting. Present study b 2 da Silva and de Andrade [9] tried to employ Fuzzy logic that is applied for a very short-term load forecasting in peak load time (at 18:00 to 21:30). Other researchers investigated very short-term loads forecasting by using Artificial Neural Network (ANN) and revealed that the Main Absolute Percentage Error (MAPE) was between the subject of the subje

The study focused on the third plan by planning and setting up the electrical load on an area, in this case, the electrical system in Java and Bali. Java Bali electricity system is the largest electricity system in Indonesia that interconnects all power plants and all loads in Java, Bali and Madura Islands [11-13]. Existing data on the Java Bali electricity system was used 40 he primary data of this study and the forecasting system that was employed is a very short term forecasting. This very short-term load forecasting has a 30-minute loading data interval that is used as the basis of how much power resources to generate, what generating arrangements that need to be operated, which plants that need to be maintained and which plants that are ready to operate.

2. Fuzzy Logics

The uncertainty concept of the 16 zzy type-2 set was first introduced by Zadeh in 1975 as the development of the ordinary fuzzy set concept of "fuzzy fuzzy" or fuzzy type 1. The fuzzy type-1 logic system is often used as the knowledge base to construct rules in a fuzzy logic system (FLS) that is often uncertain. There are three reasons why uncertainty of rules occurred, that cover: [14-16]:

- The words used as antecedents and consequents of the rules may have different meanings to different people.
- Consequents obtained from a poll of a group of experts will often differ on the same rules because the experts are not necessarily all agree on the rules.
- · Data training contains a lot of noise

The uncertainty in antecedent or consequent is translated to the uncertainty of antecedent or consequent membership function. Fuzzy logic system type-1 whose membership function is fuzzy set type-1 cannot directly resolve the uncertainty of rule type 2 fuzzy logic system, whereas antecedent or consequent function of fuzzy type-2 set membership is able to overcome the uncertainty of rules. The fuzzy set type-2 themselves have membership levels that are fuzzy.

Levels on the fuzzy set type-2 can be in a subset of secondary membership. Similar to Type-1 FLS, Type-2 FLS also includes FIS membership and defuzzification functions. Based on studies by Liu et al. [17] and Wu and Nie [18], the difference is, before the defuzzification process, there is a type reduction process that has several algorithmic methods such as Mendel Algorithm Kernic (KMA), Mendel Algorithm Kernic Enhance (EKMA), Mendel Algorithm with Initialization (EKMANI) Kernic Mendel, Iterative Algorithm with Stop Condition (IASC) and Enhance Iterative Algorithm with Stop Condition (EIASC).

2.1. Interval type-2 Fuzzy set

An interval of type-2 fuzzy set (IT-2FS) is denoted \widetilde{A} with membership function $\mu \widetilde{A}$ with $x \in X$ and $u \in Jx \subseteq$. Its characteristic can be recognized in the following Eq. 1 [18, 19].

$$\widetilde{A} = \int_{x \in X} \int_{x \in J_x} \frac{\mu \widetilde{A}(x, u)}{(x, u)} Jx \subseteq [0.1]$$
(1)

x is the primary variable having domain X; $u \in U$, a secondary variable, has a domain Jx for every $x \in X$; Jx is called the primary membership of x. Uncertainty with respect to \widetilde{A} is represented by a combination of all primary membership (Jx) called the Footprint of Uncertainty (FOU) of \widetilde{A} . The equation can be seen as allows:

$$FOU(\widetilde{A}) = \bigcup_{\forall x \in X} Jx = \{(x, u); u \subseteq [0, 1]\}$$
 (2)

Jx is an Interval with Eq. (3):

$$Jx = \left\{ (x, u); u \in \left[\underline{\mu}_{\widetilde{A}}(x), \overline{\mu}_{\widetilde{A}}(x) \right] \right\}$$
 (3)

 $FOU(\widetilde{A})$ can be expressed by Eq. (4):

$$FOU(\widetilde{A}) = \bigcup_{\forall x \in X} \left[\left\{ \mu_{\widetilde{A}}(x), \overline{\mu_{\widetilde{A}}}(x) \right\} \right] \tag{4}$$

Jx = Primary membership from x.

 $\underline{\mu}_{\tilde{A}}$ = Lower Membership Function (*LMF*) from \tilde{A} .

 $\mu_{\tilde{A}}$ = Upper Membership Function (*UMF*) from \tilde{A} .

with the graphical description can be seen in Fig. 1.

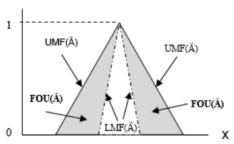


Fig. 1. FOU (graycolor), LMF (dashed line), UMF (solid line).

2.2. Interval type-2 Fuzzy inference system

Fuzzy Inference System (FIS) type-2 is almost the same as FIS type-1, using the same stages. Operation of Fuzzy Inference System type-2 can be seen in the case of giving tip "food" and service at a restaurant as described in Fig. 2.

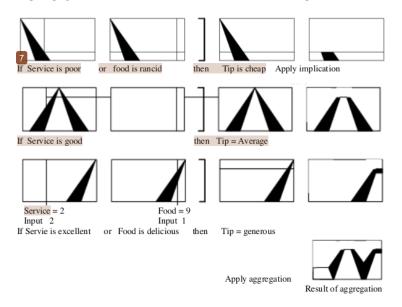


Fig. 2. Fuzzy inference system Mamdani type-2.

2.3. Deffuzzyfication

In Fuzzy Interval type-2, the logic control defuzzification process pass through the type-reducer, which has several algorithmic methods such as (KMA), (EKMAN), (EKMANI), (IASC) and (EIASC) [20]. The defuzzification process using centroid on IT-2FLS has been proposed by Mendel Kernic.

3. Research Methods

3.1. Preparation phase

In the preparation phase, it is necessary to prepare the data to be processed, for instance, the load at 17.30; 18.00; 18.30; 19.00; 19.30; 20.00; 20.30; 21.00; 21.30, on the first Friday, the second, third and fourth of October, 2013; 2014; 2015 and 2016, with the following steps:

- · Grouping of load data at times as listed above.
- Identifying the load at each time, the first Friday, second and third in the hour of forecasting

$$TD_{(i)} = \frac{\left[TD_{(i)F-3} + TD_{(i)F-2} + TD_{(i)F-1}\right]}{3}$$
 (5)

 TD_(i) = Time Difference is the average load on the First Friday, Second and Third.

$$LD_{(i)} \cdot TD_{(i)} = |SD_{(i)} - TD_{(i)}| \cdot 100$$
 (6)

 $SD_{(i)}$ is the load at the predicted time.

- Finding the value TLD_(i) (The typical Time Load Difference) by calculating the average load of LD_(i) on each Friday in October at the hour predicted by the same time last year.
- Calculating VLD (Variation Load Difference at Time), which is being forecasted.

$$\overline{VLD_{(i)}} = LD_{(i)} - TLD_{(i)} \tag{7}$$

3.2. Processing stage

The processing stage was conducted for modelling very short term load forecasting using Interval Type-2 Fuzzy Inference System, which was carried out by using several steps:

- Creating a membership function input interval type-2 fuzzy logic system such as input X dan Y and output membership function such as Z for time to be predicted with the following conditions:
 - $X: VLD_{MAX(i)}$ the same time in the day prior to the forecast time.
 - Y: $VLD_{MAX(i)}$ the previous time (adjacent) in the same time type in the forecasting year.
 - Z: Forecasting VLD MAX(i) at time to be forecasted.



- Planning the membership function of the type-2 fuzzy logic system interval such as antecedent (X, Y) and consequent (Z) to get the best value of the footprint of uncertainty
- Making fuzzy rules interval type-2 fuzzy inference system (IT-2FIS) as follows:

IF X is A_i AND Y is B_i THEN Z is C_i

- Implementing the AND operation at the fuzzy inference system type-2 (IT-2FIS)
 - · Implementing MIN's implication function on fuzzy rules.
 - Applying MAX composition to each fuzzy rule implication result.
 - Calculating the value of defuzzification through the type reducer using Mendel Kernic Algorithm to get the value of Forecast VLD_{MAX}.

3.3. Phase after processing

The advanced stage is looking for peak load value and forecasting error from Forecast VLD_{MAX} , which was carried out as follows:

3.3.1 Calculating the forecast load difference for the forecasted time

After knowing the value of VLD_{MAX} , the next step is to look for forecasting LD_{MAX} in each year of forecast, using the following formula:

$$LD_{MAX(i)} = VLD_{MAX(i)} + TLD_{MAX(i)}$$
(8)

3.3.2. Calculating forecasting error

After knowing the forecasting value in the year sought, the calculation of errors (*Error*%) in each forecast year is carried out using the following formula:

$$Error\% = \frac{P_{forecast} - P_{actual}}{P_{actual}} \times 100\%$$
(9)

$$Error\% = \frac{P_{\max(i)} - MaxSD_{(i)}}{MaxSD_{(i)}} \times 100\%$$
(10)

4. Results and Discussion

Explanation of very short term load forecasting method above is one applicable method. However, the above method can be developed using a basic time analysis basis on four days before forecasting day with the same hour, or 4 hours before the forecast hour and so on. In short-term electricity load forecasting, some researchers have used IT-1 FIS and IT-2 FIS in order to get the results of forecasting errors that are smaller compared to other methods. In the short-term electricity load forecasting method, some researchers used different time analysis by using 4 days before the forecast day, there are also those who use other days with the same character as forecasting days [2, 3].

This study used data loading of Java Bali electrical system [11-13, 21] by investigating loads on the first, second, third and fourth Fridays in October 2012 until 2016 at peak load time (at 17.30 to 21.00) to find the value of *TD*, *LD*, and *VLD*. The calculation results are in Tables 1 and 2. The *TD* value is derived from



the average value of the sum of the Friday's loads to the first, the second, and the third Fridays. The value of LD was obtained from the difference value of LD and the prediction of 4^{th} Friday. Table 1 shows the search for LD values in 2012 and Table 2 shows the value of TD and LD in forecasting year 2013.

Table 1. Calculation of TD and TLD in 2012.

Time		2012	(MW)		TD	LD	
Time	F-3	F-2	F-1	F	ID	LD	
17.30	18,768.45	19,895.13	20,068.45	19,768.45	19,577.34	0.98	
18.00	19,344.00	20,698.57	20,344.00	19,911.00	20,128.86	-1.08	
18.30	19,667.00	20,587.89	20,839.00	20,178.00	20,364.63	-0.92	
19.00	20,400.00	20,655.77	21,561.00	20,381.00	20,872.26	-2.35	
19.30	20,711.00	20,625.11	22,003.00	20,634.00	21,113.04	-2.27	
20.00	21,345.00	20,359.19	22,421.00	20,960.00	21,375.06	-1.94	
20.30	21,625.00	20,123.86	22,594.00	21,321.00	21,447.62	-0.59	
21.00	20,987.30	19,644.05	21,707.14	20,907.14	20,779.50	0.61	
21.30	20,266.36	19,256.62	21,266.36	20,261.36	20,263.11	-0.01	

F = Friday will be forecasted; F-3 = First Friday; F-2 = Second Friday; F-1 = Third Friday.

Table 2. Calculation of TD and TLD in 2013.

m:		2013	(MW)		TD.	LD	
Time	F-3	F-2	F-1	F	TD		
17.30	21,068.45	21,304.92	21,868.45	21,568.45	21,413.94	0.72	
18.00	21,344.00	22,145.91	22,044.00	21,811.00	21,844.64	-0.15	
18.30	21,467.00	22,132.62	22,239.00	22,378.00	21,946.21	1.97	
19.00	21,709.00	22,068.45	22,561.00	22,781.00	22,112.82	3.02	
19.30	22,311.00	21,911.98	22,903.00	23,034.00	22,375.33	2.94	
20.00	22,645.00	21,807.14	23,121.00	23,760.00	22,524.38	5.49	
20.30	21,925.00	21,594.28	23,594.00	23,399.00	22,371.09	4.59	
21.00	21,787.30	21,266.36	22,907.14	22,707.14	21,986.93	3.28	
21.30	21,466.36	20,695.91	22,766.36	22,261.36	21,642.88	2.86	

 $F = \overline{Friday \ will \ be \ forecasted; \ F-3 = First \ Friday; \ F-2 = Second \ Friday; \ F-1 = Third \ Friday.}$

After obtaining the value of TD and LD, TLD and VLD for 2014 were calculated (see Table 3). TLD for 2014 value was obtained from the average value of LD in 2013 and LD 2012. The value of VLD for 2014 was obtained from the difference between LD and TLD value in 2014. Using the same method, the data gained were used to calculate 2015 forecast using 2016 funds, as shown in Table 4.

Table 3. Calculation of TD, LD, TLD and VLD in 2014.

Time		2014	(MW)		- TD	LD	TLD	VLD
1 ime	F-3	F-2	F-1	F	10	ш	HD	VLD
17.30	21,704.61	22,133.11	22,004.61	22,004.61	21,947.44	0.26	0.85	-0.59
18.00	21,975.00	22,901.87	22,631.00	22,631.00	22,502.62	0.57	-0.62	1.19
18.30	22,181.00	22,821.94	22,812.00	22,812.00	22,604.98	0.92	0.53	0.39
19.00	22,353.00	22,704.61	23,191.00	23,191.00	22,749.54	1.94	0.33	1.61
19.30	22,411.00	22,941.31	23,878.00	23,878.00	23,076.77	3.47	0.34	3.13
20.00	22,767.00	22,779.65	23,974.00	23,974.00	23,173.55	3.45	1.77	1.68
20.30	22,453.00	22,636.61	23,573.00	23,573.00	22,887.54	2.99	2.00	0.99
21.00	21,779.65	22,286.85	23,479.65	23,479.65	22,515.38	4.28	1.94	2.34
21.30	21,586.85	21,548.88	23,186.85	23,186.85	22,107.53	4.88	1.42	3.46

F=Friday will be forecasted; F-3 = First Friday; F-2 = Second Friday; F-1 = Third Friday.

Table 4. Calculation of TD, LD, TLD and VLD by 2015 and 2016.

Time		201:	5		2016					
1 ime	TD	LD	TLD	VLD	TD	LD	TLD	VLD		
17.30	23.333,39	-2,44	0,49	-2,93	23.123,47	3,35	-1,09	4,44		
18.00	23.758,44	-3,44	0,21	-3,65	23.847,61	1,14	-1,44	2,58		
18.30	23.845,54	-2,85	1,44	-4,30	23.939,25	1,88	-0,97	2,85		
19.00	23.423,50	-0,44	2,48	-2,92	23.769,09	4,75	0,75	4,00		
19.30	23.144,19	0,18	3,21	-3,02	23.489,09	6,43	1,83	4,60		
20.00	22.782,98	1,84	4,47	-2,63	23.434,67	3,68	2,65	1,03		
20.30	22.561,00	4,15	3,79	0,36	23.531,12	0,98	3,57	-2,60		
21.00	22.652,07	5,67	3,78	1,89	23.034,78	0,77	4,98	-4,20		
21.30	22.107,57	6,67	3,87	2,80	22.556,19	0,93	5,78	-4,84		

The obtained X value is exactly similar to VLD for 2014 and the load per hour during load time, which was predicted in 2015 is VLD for 2015. It then becomes consequent or Z. In addition, Y value will be obtained from VLD value for 2015 at near-close time. For the 2016 forecasting year, the processed value is the VLD value of 2015 as the mat lab input on the antecendent X, while the value of its output/consequent (Z) is VLD 2016. The value of Y will be obtained in the same way for 2015. After gaining the data in Tables 5 and 6, the next step is to include the formation of Fuzzy basic rules for the forecasting in 2015 and 2016 by using the data input X, Y, and Z whose results shown in Tables 7 to 12. The membership function value was obtained by entering the X value in the membership function as listed below and a high membership degree is inputted as the antecedents and its consequence values.

The input variables (X and Y) and the output variable (Z) consist of 11 sets of Fuzzy as follows:

5 43 10110 43.	
 Negative Very Big (NVB) 	with a values -6 up to -4
 Negative Big (NB) 	with a values -5 up to -3
 Negative Medium (NM) 	with a values -4 up to -2
 Negative Small (NS) 	with a values -3 up to -1
 Negative Very Small (NVS) 	with a values -2 up to 0
 Zero (ZE) 	with a values -1 up to 1
 Positive Very Small (PVS) 	with a values 0 up to 2
 Positive Small (PS) 	with a values 1 up to 3
 Positive Medium (PM) 	with a values 2 up to 4
 Positive Big (PB) 	with a values 3 up to 5
 Positive Very Big (PVB) 	with a values 4 up to 6

Table 5. Input data for fuzzy forecasting 2015.

	-		•		_
Time	2014	2015	In	put	Output
1 iine	VLD	VLD	X	Y	Z
17.30	-0.5884	-2.9261	-0.5884	-3.6531	-2.9261
18.00	1.1886	-3.6531	1.1886	-2.9261	-3.6531
18.30	0.3903	-4.2956	0.3903	-2.9174	-4.2956
19.00	1.6065	-2.9174	1.6065	-4.2956	-2.9174
19.30	3.1346	-3.0229	3.1346	-2.6334	-3.0229
20.00	1.6822	-2.6334	1.6822	-3.0229	-2.6334
20.30	0.9927	0.3596	0.9927	1.8918	0.3596
21.00	2.3378	1.8918	2.3378	0.3596	1.8918
21.30	3.4576	2.8036	3.4576	1.8918	2.8036

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Table 6. Input data for fuzzy forecasting 2016.

Time	2015	2016	In	put	Output
1 ime	VLD	VLD	X	Y	Z
17.30	-2.9261	4.4380	-2.9261	-4.8432	4.4380
18.00	-3.6531	2.5752	-3.6531	4.4380	2.5752
18.30	-4.2956	2.8478	-4.2956	2.5752	2.8478
19.00	-2.9174	3.9985	-2.9174	2.8478	3.9985
19.30	-3.0229	4.5996	-3.0229	3.9985	4.5996
20.00	-2.6334	1.0344	-2.6334	4.5996	1.0344
20.30	0.3596	-2.5978	0.3596	1.0344	-2.5978
21.00	1.8918	-4.2031	1.8918	-2.5978	-4.2031
21.30	2.8036	-4.8432	2.8036	-4.2031	-4.8432

Table 7 reveals that *X* has 2 degrees of membership function and was taken as the value that has the highest degree that is similar to results of Tables 8 and 9 for forecasting year 2015.

The 2016 forecasting has the value of membership function of the value of X, Y, and Z as shown in Tables 10 to 12.

Table 7. Establishment of the basic rules for input value of *X* for 2015.

Time	V <mark>alu</mark> e					N	1embershi	p function	(µ)				Sets
Time	X	NVB	NB	NM	NS	NVS	ZE	PVS	PS	PM	PB	PVB	X
17.30	(0,5884)					0,6115	0,3885						NVS
18.00	1,1886							0,7820	0,2180				PVS
18.30	0,3903						0,6470	0,3530					ZE
19.00	1,6065							0,3810	0,6190				PS
19.30	3,1346									0,8220	0,1780		PM
20.00	1,6822							0,4120	0,5880				PS
20.30	0,9927						0,0178	0,9822					PVS
21.00	2,3378								0,8110	0,1890			PS
21.30	3,4576									0,5934	0,4066		PM

Table 8. Establishment of the basic rules for input value of Y in 2015.

T:	V <mark>a1u</mark> e					Me	mbership fui	nction (µ)					Sets
Time	Y	NVB	NB	NM	NS	NVS	ZE	PVS	PS	PM	PB	PVB	Y
17.30	(3,6531)		0,6720	0,328									NB
18.00	(2,9261)			0,953	0,047								NM
18.30	(2,9174)			0,911	0,089								NM
19.00	(4,2956)		0,2881	0,7119									NM
19.30	(2,6334)			0,622	0,378								NM
20.00	(3,0229)		0,1320	0,868									NM
20.30	1,8918							0,4350	,5650				PS
21.00	0,3596						0,6510	0,3490					ZE
21.30	1,8918							0,7500	0,2500				PVS

Table 9. Establishment of the basic rules for input Z value in 2015.

TP:	V <mark>alu</mark> e		Membership function (μ)											
Time	Z	NVB	NB	NM	NS	NVS	ZE	PVS	PS	PM	PB	PVB	Sets Z	
17.30	(2,9261)			0,9530	0,0470								NM	
18.00	(3,6531)		0,6720	0,3280									NB	
18.30	(4,2956)		0,2881	0,7119									NM	
19.00	(2.9174)			0,9110	0,0890								NM	
19.30	(3,0229)		0,1320	0,8680									NM	
20.00	(2,6334)			0,6220	0,3780								NM	
20.30	0,3596						0,6510	0,3490					ZE	
21.00	1,8918							0,4350	0,5650				PS	
21.30	2,8036							0,7500	0,2500				PVS	

Table 10. Establishment of the basic rules for input X value in 2016.

Tr:	V <mark>a1u</mark> e		Membership function (μ)											
Time	X	NVB	NB	NM	NS	NVS	ZE	PVS	PS	PM	PB	PVB	X	
17.30	(2,9261)			0,9530	0,0470								NM	
18.00	(3,6531)		0,6720	0,3280									NB	
18.30	(4,2956)		0,2881	0,7119									NM	
19.00	(2,9174)			0,9110	0,0890								NM	
19.30	(3,0229)		0,1320	0,8680									NM	
20.00	(2,6334)			0,6220	0,3780								NM	
20.30	0,3596						0,6510	0,3490					ZE	
21.00	1,8918							0,4350	0,5650				PS	
21.30	2,8036							0.7500	0.2500				PVS	

Table 11. Establishment of the basic rules for input value Y in 2016.

Time	V <mark>a1u</mark> e		Membership function (μ)											
1 ime	Y	NVB	NB	NM	NS	NVS	ZE	PVS	PS	PM	PB	PVB	Y	
17.30	(4,8432)	0,8780	0,122										NVB	
18.00	4,4380										0,6570	0,3430	PB	
18.30	2,5752								0,4850	0,5150			PM	
19.00	2,8478								0,2570	0,7430			PM	
19.30	3,9985									0,1870	0,8130		PB	
20.00	4,5996										0,4782	0,5218	PVB	
20.30	1,0344							0,8910	0,1090				PVS	
21.00	(2,5978)			0,6940	0,306								NM	
21.30	(4,2031)	0,2590	0,741										NB	

Table 12. Establishment of the basic rules for input Z value in 2016.

Time	V <mark>a1u</mark> e	Membership function (μ)									Sets		
Time	Z	NVB	NB	NM	NS	NVS	ZE	PVS	PS	PM	PB	PVB	Z
17.30	4,4380										0,6570	0,3430	PB
18.00	2,5752								0,4850	0,5150			PM
18.30	2,8478								0,2570	0,7430			PM
19.00	3,9985									0,1870	0,8130		PB
19.30	4,5996										0,4782	0,5218	PVB
20.00	1,0344							0,8910	0,1090				PVS
20.30	(2,5978)			0,6940	0,3060								NM
21.00	(4,2031)	0,2590	0,741										NB

From the existing data-membership function, a table of basic rules for the forecasting year of 2015 and 2016 was then made as shown respectively in Tables 13 and 14.

From the basic rules of forecasting, a table conversion of the basic rules of forecasting in 2015 and 2016 for Matlab software code was made, as can be seen in Tables 15 and 16.

Table 13. Basic forecasting rules table for 2015.

	11	141	nc 13.	Dasi	ciorca	isting .	i uics ta	DIC 101	2015.		
X/Y	NVB	NB	NM .	NS	NVS	ZE	PVS	PS	PM	PB	PVB
NVB		NM									
NB											
NM											
NS NVS ZE PVS PS											
NVS		NM									
\mathbf{ZE}			NM								
PVS			NB					ZE			
PS			NM			PS					
\mathbf{PM}			NM				PVS				
PB											
PVB											

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Table 14. Basic forecasting rules table for 2016.

	13										
X/Y	NVB	NB	NM	NS	NVS	ZE	PVS	PS	PM	PB	PVB
NVB											
NB									PB	PM	
										PVB/	
NM	PB								PM	PVS	
NM NS											
NVS											
$\mathbf{Z}\mathbf{E}$							NM				
PVS		NVB									
PS PM			NB								
\mathbf{PM}											
PB											
PVB											

Table 15. Conversion table of 2015 basic rules for Matlabsoftware code.

No. of	Antecendent		Consequent	No. of	Antecendent		Consequent	
rules	X	Y	\mathbf{z}	rules	\boldsymbol{X}	Y	\mathbf{z}	
1	NVS	NB	NM	1	5	2	3	
2	PVS	NM	NB	2	7	3	2	
3	ZE	NM	NM	3	6	3	3	
4	PS	NM	NM	4	8	3	3	
5	PM	NM	NM	5	9	3	3	
6	PS	NM	NM	6	8	3	3	
7	PVS	PS	ZE	7	7	8	6	
8	PS	ZE	PS	8	8	6	8	
9	PM	PVS	PVS	9	9	. 7	7	

Table 16. Conversion table of 2016 basic rules for Matlab software code.

No. of	Antecendent		Consequent	No. of	Antecendent		Consequent	
rules	X	Y	Z	rules	X	Y	Z	
1	NM	NVB	PB	1	3	1	10	
2	NB	PB	PM	2	2	10	9	
3	NM	PM	PM	3	3	9	9	
4	NM	PM	PB	4	3	9	10	
5	NM	PB	PVB	5	3	10	11	
6	NM	PVB	PVS	6	3	11	7	
7	ZE	PVS	NM	7	6	7	3	
8	PS	NM	NB	8	8	3	2	
9	PVS	NB	NVB	9	7	2	1	

The gained data were processed by using Matlab to obtain the VLD error value, for the forecasting year 2015 and 2016 by using IT-1 FIS and using IT-2 FIS. The Matlab results above were then inputted to the VLD forecasting value to get the value of the load and its error value. The results of the forecasting on VLD and the error value can be seen in Tables 17 and 18.

Meanwhile, the average value for each of the forecasting methods are shown in Table 19. From Table 19, it can be seen that in 2015 and 2016 and with different forecasting methods for forecasting using IT-1 FIS, there was 0.94% increase in forecasting errors in 2015 and 1.27% in 2016. The same thing happened for the use of IT-2 FIS forecasting method showing that there was an increase in forecasting errors in 0.70% in 2015 and 0.72% in 2016. Table 19 also showed that the use of the FIS IT-2 method has a smaller forecasting error value compared to the use of IT-1 FIS since IT-2 FIS provides a greater area of membership with the presence of FOU. This gives higher forecasting accuracy. Graphically, the error forecasting in 2015 can be seen in Fig. 3. In addition, the graphic of the error forecasting in 2016 is shown in Fig. 4. From the the discussion, it can be concluded that the use of IT-2 FIS, which has never been used to forecast very short term loads by determining

the electric load on the previous date with the same character on Friday before October forecasting Friday performs forecasting errors that are smaller than using other forecasting methods.

Table 17. Calculation of load and forecasting value of 2015 using IT-1-FIS and IT-2 FIS.

	I	Γ-1 FIS - 2015	5	
Output	Forecast	Forecast	Actual	Error
Forecast	LD	P'(MW)	(MW)	(%)
-3,0000	-2,5090	22.747,96	22.765,20	0,0757
-3,7699	-3,5616	22.912,25	22.940,00	0,1210
-3,4109	-1,9692	23.375,97	23.165,00	0,9107
0,0000	2,4811	24.004,67	23.321,30	2,9302
-1,5823	1,6256	23.520,41	23.187,00	1,4379
-3,3518	1,1181	23.037,73	23.201,40	0,7054
0.000,0	3,7949	23,417,16	23,498,30	0,3453
1,6280	5,4072	23.876.90	23,936,65	0.2496
1,0050	4,8749	23.185,29	23.582,91	1,6860
,			Sum	8,4620
			Average	0,9402
	ľ	Γ-2 FIS - 2015	5	
Output	Forecast	Forecast	Actual	Error
Forecast	LD	P'(MW)	(MW)	(%)
-3,0000	-2,5090	22.747,96	22.765,20	0,0757
-3,8301	-3,6218	22.897,95	22.940,00	0,1833
-3,3731	-1,9314	23.384,98	23.165,00	0,9496
0,0000	2,4811	24.004,67	23.321,30	2,9302
-3,0000	0,2079	23.192,30	23.187,00	0,0229
-3,2857	1,1842	23.052,79	23.201,40	0,6405
0,0000	3,7949	23.417,16	23.498,30	0,3453
1,6869	5,4661	23.890,25	23.936,65	0,1939
1,7510	5,6209	23.350,21	23.582,91	0,9867
			Sum	6,3282
			Average	0.7031

Table 18. Calculation of load and forecasting value of 2016 using IT-1-FIS and IT-2 FIS.

	I	T-1 FIS - 201	6	
Output	Forecast	Forecast	Actual	Error
Forecast	LD	P'(MW)	(MW)	(%)
4,0014	2,9141	23.797,30	23.898,27	0,4225
3,0000	1,5628	24.220,31	24.119,00	0,4200
0,0000	-0,9691	23.707,26	24.389,00	2,7953
3,5001	4,2522	24.779,80	24.898,27	0,4758
4,9091	6,7376	25.071,69	24.999,00	0,2908
2,7279	5,3732	24.693,88	24.297,00	1,6334
-3,0000	0,5747	23.666,36	23.761,00	0,3983
-4,0012	0,9756	23.259,51	23.213,00	0,2004
0,0000	5,7778	23.859,44	22.767,00	4,7984
			Sum	11,434
			Average	1,2705
	I	T-2 FIS - 201	6	
Output	Forecast	Forecast	Actual	Error
Forecast	LD	P'(MW)	(MW)	(%)
4,0851	2,9978	23.816,66	23.898,27	0,3415
3,0003	1,5631	24.220,38	24.119,00	0,4203
0,0000	-0,9691	23.707,26	24.389,00	2,7953
3,5922	4,3443	24.801,69	24.898,27	0,3879
4,3612	6,1897	24.942,99	24.999,00	0,2240
2,6751	5,3204	24.681,50	24.297,00	1,5825
-3,0000	0,5747	23.666,36	23.761,00	0,3983
-4,0006	0,9762	23.259,65	23.213,00	0,2010
-4,7000	1,0778	22.799,30	22.767,00	0,1419
			Sum	6,4927

Table 19. Average comparison of usage IT-1 FIS and IT-2 FIS.

Time	IT-1	-FIS	Time	IT-2-FIS		
Time	2015	2016	- 1 ime	2015	2016	
17.30	80,0	0,42	17.30	0,08	0,34	
18.00	0,12	0,42	18.00	0,18	0,42	
18.30	0,91	2,80	18.30	0,95	2,80	
19.00	2,93	0,48	19.00	2,93	0,39	
19.30	1,44	0,29	19.30	0,02	0,22	
20.00	0,71	1,63	20.00	0,64	1,58	
20.30	0,35	0,40	20.30	0,35	0,40	
21.00	0,25	0,20	21.00	0,19	0,20	
21.30	1,69	4,80	21.30	0,99	0,14	
Sum	8,46	11,43	Sum	6,33	6,49	
Average	0,9402	1,2705	Average	0,7031	0,7214	
Average 2		1,1054	Average 2		0,7123	
Years			Years			

Error Forecasting at 2015

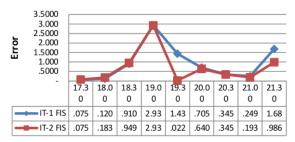


Fig. 3. Error forecasting 2015.

Error Forecasting at 2016

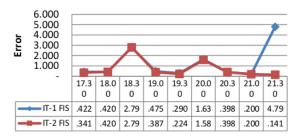


Fig. 4. Graph of forecasting error 2016.

5. Conclusions

From the above analysis, a very short term load forecasting on the fourth Friday on October 2015 using IT-1 FIS of Tained the average error is 0.94%, while using IT-2 FIS is equal to 0.70%. In 2016, a very short term load forecasting on the fourth October using IT-1 FIS obtained 1.27% average error while using IT-2 FIS, is equal to 0.72%. The average forecasting error of very short-term using IT-1 FIS in 2015 and 2016 is 1.11%, meanwhile, the use of IT-2 FIS obtained 0.71% of average forecasting error. It

can be concluded from the results that a very short term load forecasting can be done using IT-2 FIS with a smaller error value compared to the use of IT-1 FIS. In future research, a deeper collection of antecedents' data by using a day adjacent to the predicted day hours can be done by using other Artificial Intelligent.

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