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Penulis	Irwan Alnarus Kautsar, M. Ruslianor Maika	
Nama seminar/ konferensi/ simposium (lengkap dan singkatannya jika ada)	The 1st Paris Van Java International Seminar on Computer, Science, Engineering, and Technology, 2019. (PVJ-IS)	
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### The use of User-centered Design Canvas For Rapid Prototyping

Irwan Alnarus Kautsar, M. Ruslianor Maika

Universitas Muhammadiyah Sidoarjo

### **Abstract**

This paper presents the use of User-centered Design Canvas to help students design the user experience (UX) on the designated Collaborative Projects. The Collaborative Project itself has been conducted by students with multi-discipline backgrounds. The User-centered design itself was widely used as an approach to software development in order to achieve better alignment between the user experience and the business goal. Adopting Business Model Canvas, the User-centered Design Canvas was introduced as an acceleration tool for rapid prototyping and ensures the effectiveness and efficient manner for the sake of user satisfaction. As the results from the questionnaire, more than 78% of users express the benefits of the current adaptation of User-centered Design Canvas. Also from the Log Metric Analysis, users have completed a designated task under 5 minutes with minimum repetition. This indicates that the use of proposed adaptation is easy to use and shows the effectiveness of the User-Centered Design Canvas for rapid prototyping. (Approx. 156 words)

Keywords: user centered design, Prototyping, User Experience

Topic: Engineering and Technology

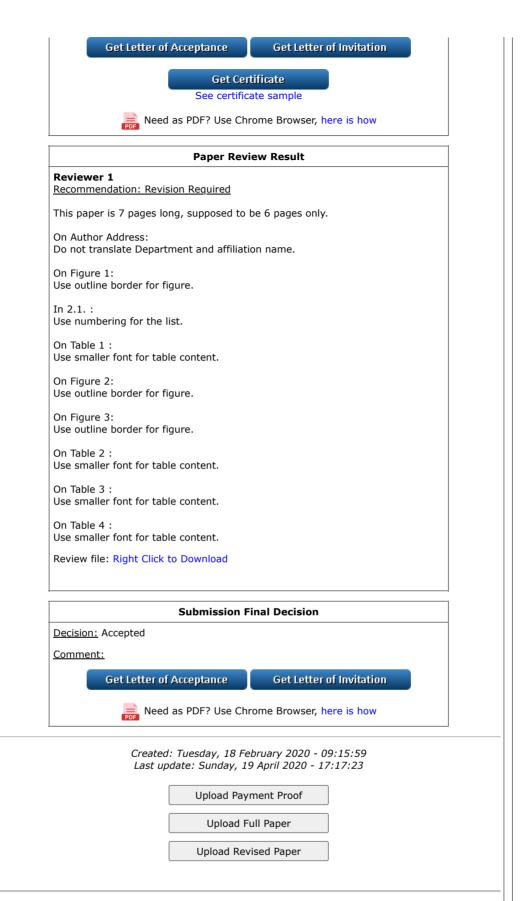
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## A New 4-D Multistable Hyperchaotic Two-Scroll System, its Bifurcation Analysis, Synchronization and Circuit Simulation

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**1764** (2021) 012204 doi:10.1088/1742-6596/1764/1/012204

# Four-scroll chaotic attractor and four-scroll hyperchaotic attractor generated from a new four-dimensional dynamical system

### Khaled Benkouider<sup>1\*</sup>, Toufik Bouden<sup>1</sup>, Mustak E. Yalcin<sup>2</sup>, Aceng Sambas<sup>3</sup>, Mujiarto<sup>3</sup>, Muhamad Ali Pahmi<sup>4</sup>, Akhmad Sutoni<sup>5</sup> and Widjajani<sup>6</sup>

<sup>1</sup>Non Destructive Testing Laboratory, Automatic Department, Jijel University, Algeria

**Abstract.** In this paper, a new 4-D hyperchaotic system with one equilibrium point is first introduced. It contains ten terms with three quadratic nonlinearities. Of particular interest is that this novel system can generate periodic attractor, quasi-periodic attractor, four-scroll chaotic attractor and four-scroll hyperchaotic attractor with the variation of one of its parameters. Major dynamical properties of the new system are investigated such as sensitivity to the initial conditions, dissipativity, equilibrium point stability, Kaplan-Yorke dimension, Lyapunov exponents spectrum and bifurcation diagram. In addition, an equivalent electronic circuit schematic is implemented using Multisim software; the obtained results confirm the feasibility of the proposed system.

Keywords: Chaos, hyperchaos, chaotic system, four-scroll attractor, Lyapunov exponent, bifurcation, electronic circuits

### 1. Introduction

In the past 60 years, research on chaotic systems has a great intention from scientific communities, especially after the famous work of the American meteorologist Edward Lorenz in 1963 [1]. He identified the main property of the chaotic systems, which is the high sensitivity to the initial conditions. A little variation in the initial values of the chaotic system lead to a very different and unpredictable behaviours. The high complex behaviour of this kind of systems make them very useful in many field of sciences such as secure communication [2-5].

The main tool to characterize a chaotic behaviour of a dynamical system is the Lyapunov exponents. More clearly, a Lyapunov exponent is calculated by considering two adjacent initial values of a dynamical system. If this system exhibit a chaotic behaviour, the trajectories generating from those initial values will diverge exponentially, the parameter that characterize the rate of that divergence is a Lyapunov exponent. In fact, for each of the state-space dimensions there is a

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Journal of Physics: Conference Series

### Computer Modelling of the Information Properties of Hyper Chaotic Lorenz System and Its Application in Secure Communication System

**Volodymyr Rusyn**<sup>1</sup>, Mujiarto<sup>2\*</sup>, Mustafa Mamat<sup>3</sup>, Firmansyah Azharul<sup>4</sup> and W. S. Mada Sanjaya<sup>5</sup>, Aceng Sambas<sup>2</sup>, Estiyan Dwipriyoko<sup>6</sup> and Akhmad Sutoni<sup>7</sup>

**Abstract.** This paper presents computer modeling, analysis and research of the hyper-chaotic Lorenz system based on programming interface that has been developed in LabView software environment. This study allows for generating and research of the main information properties of hyper-chaotic Lorenz system, focusing on time distribution of the four chaotic coordinates, phase portraits and Lyapunov exponents. The programming interface demonstrates the algorithm of masking and decrypt of the information carrier.

Keywords: Nonlinear, hyper-chaotic, Lorenz, LabView

#### 1. Introduction

The generation and application of chaotic attractors have been studied with increasing interest and have become a central topic in research due to its great potential in chaos communication technology [1]-[5]. Chaos theory has been established since the 1970's due to its applications in many different research areas, such as electronic circuits [6]-[7], secure communication systems [8]-[9], robotics [10]-[11], optics [12]-[13], economy [14]-[15], biology [16]-[17], etc.

In order to obtain hyper-chaos, two important requisites are as follows:

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# A New 4-D Multistable Hyperchaotic Two-Scroll System, its Bifurcation Analysis, Synchronization and Circuit Simulation

### Sundarapandian Vaidyanathan<sup>1\*</sup>, Aceng Sambas<sup>2</sup>, Mujiarto<sup>2</sup>, Mustafa Mamat<sup>3</sup>, Wilarso<sup>4</sup>, Mada Sanjaya W.S.<sup>5</sup>, Akhmad Sutoni<sup>6</sup> and I Gunawan<sup>7</sup>

**Abstract.** A new 4-D hyperchaotic two-scroll system with three quadratic nonlinearities and a cubic nonlinearity is proposed in this paper. The dynamical properties of the new hyperchaotic system are described in terms of phase portraits, Lyapunov exponents, Kaplan-Yorke dimension, symmetry, dissipativity, etc. We also establish that the new hyperchaotic system has multistability with coexisting attractors. As a control application, we use integral sliding mode control for active self-synchronization of the new hyperchaotic systems as master-slave systems. As an engineering application, an electronic circuit design of the new hyperchaotic two-scroll system is developed in MultiSIM, which confirms the feasibility of the system.

Keywords: Chaos, hyperchaos, hyperchaotic systems, sliding mode control, synchronization, etc.

### 1. Introduction

Chaos theory deals with nonlinear dynamical systems exhibiting high sensitivity to small changes in initial conditions [1-2]. Mathematically, chaotic systems are characterized by the presence of at least one positive Lyapunov exponent. Chaotic systems have applications in several engineering areas such as chemical reactors [3-4], neuron systems [5-6], mechanical systems [7-8], circuits [9-11], oscillators [12-13], neural networks [14-15], etc.

Hyperchaotic systems are defined as chaotic systems having two or more positive Lyapunov exponents. The trajectories of hyperchaotic systems can expand in two different directions corresponding to the two positive Lyapunov exponents. Hyperchaotic systems have important engineering applications such as cryptosystems [16-17], secure communication systems [18-19], etc.

In this work, we report a new 4-D hyperchaotic two-scroll system with three quadratic nonlinearities and a cubic nonlinearity. The dynamical properties of the new hyperchaotic system are described in terms of MATLAB phase portraits, Lyapunov exponents, Kaplan-Yorke dimension,

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# The use of User-centered Design Canvas for Rapid Prototyping

### Irwan Alnarus Kautsar<sup>1\*</sup> and M. Ruslianor Maika<sup>2</sup>

<sup>1</sup>Program Studi Informatika, Fakultas Sains dan Teknologi, Universitas Muhammadiyah Sidoarjo

<sup>2</sup>Program Studi Perbankan Syariah, Fakultas Agama Islam, Universitas Muhammadiyah Sidoarjo

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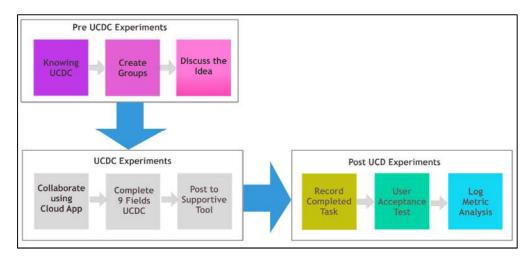


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### 3. Results and Discussions

This section will briefly discuss the questionnaire result about the use of UCDC for rapid prototyping.

### 3.1. Results

Before using or learning UCDC, all participants have been requested to fill the designated questionnaire. Table 2 shows the questions for the questionnaire.

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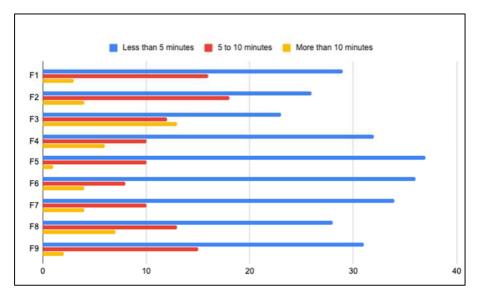


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User Centered Design Canvas (UCDC) helps do more rapidly at prototyping and define more in depth understanding about the basic need while designing User Experiences. Also, the use of cloud application and supportive tools enable collaboration among students that implement distance learning while at pandemic era. For future works, it needs to study to integrate the UCDC (for design UX) with other prototyping tools for UI design.

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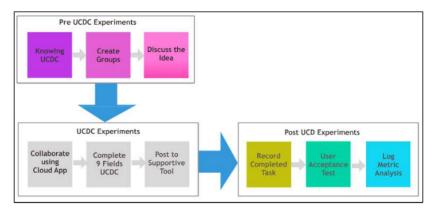


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### 7

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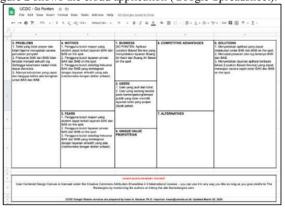




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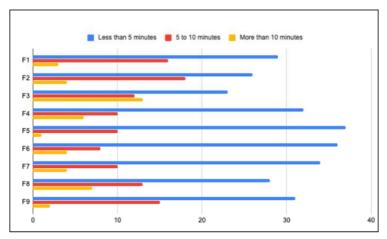


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: The use of User-centered Design Canvas for Rapid Prototyping

Penulis

: Irwan Alnarus Kautsar, M. Ruslianor Maika

Status Pengusul: Penulis Utama

Identitas Jurnal Ilmiah:

a. Judul Prosiding: Journal of Physics: Conference Series: 1st Paris Van Java International Seminar on

Computer, Science, Engineering and Technology (PVJ ISComSET) 2020

b. ISBN/ISSN

: 1742-6596

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: 15-16 Juli 2020

d. Penyelenggara: Universitas Muhammadiyah Tasikmalaya (UMTAS)

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Judul Artikel

: The use of User-centered Design Canvas for Rapid Prototyping

Penulis

: Irwan Alnarus Kautsar, M. Ruslianor Maika

Status Pengusul: Penulis Utama

Identitas Jurnal Ilmiah:

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Unsur persyaratan prosiding internasional terpenuhi.

Tentang ruang lingkup & kedalaman pembahasan:

Pembahasan User Design Canvas cukup dalam

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